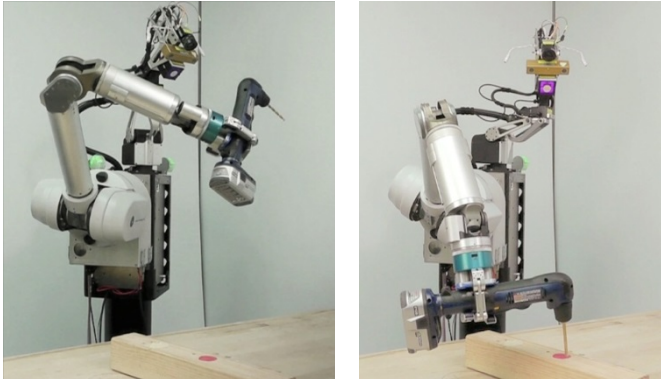
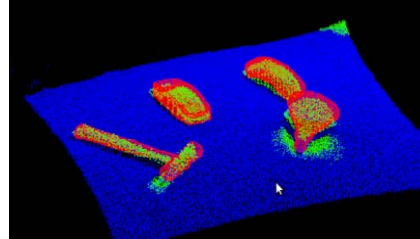


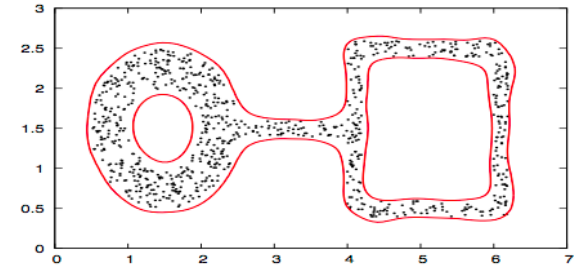
Dexterous robotic manipulation



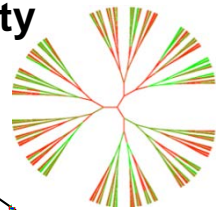
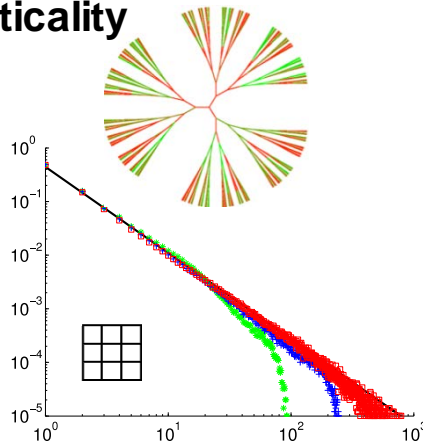
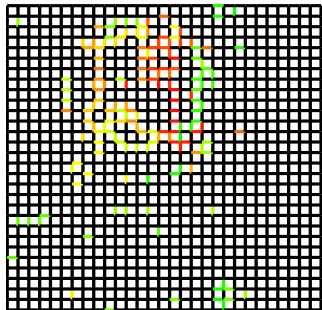
Sensor processing



Machine learning



Complex systems and self-organized criticality



Human and robotic movement generation

